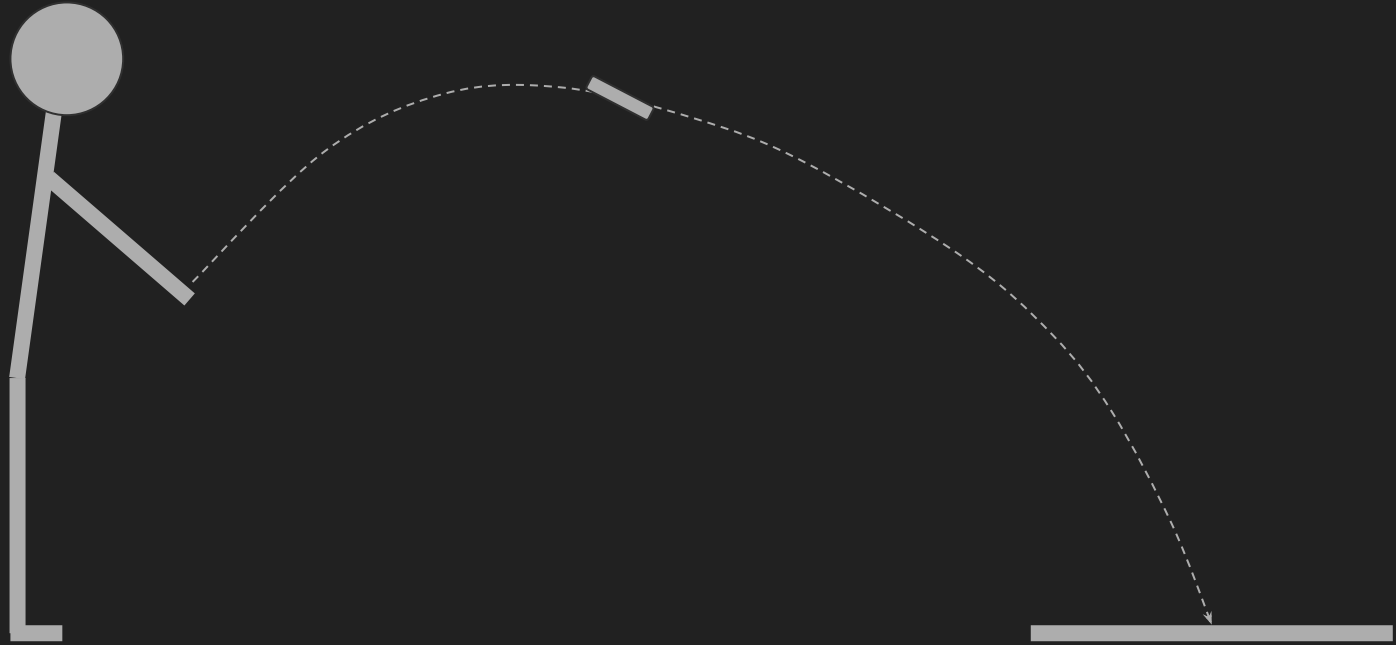


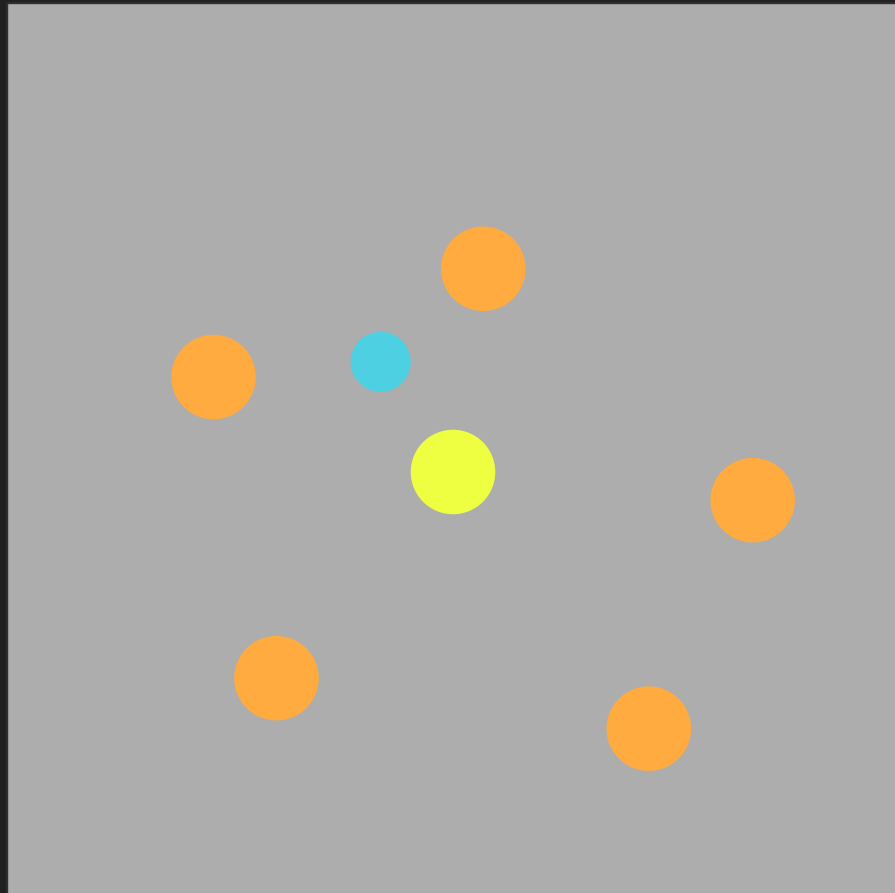
JavaScript, GPU
et palet breton

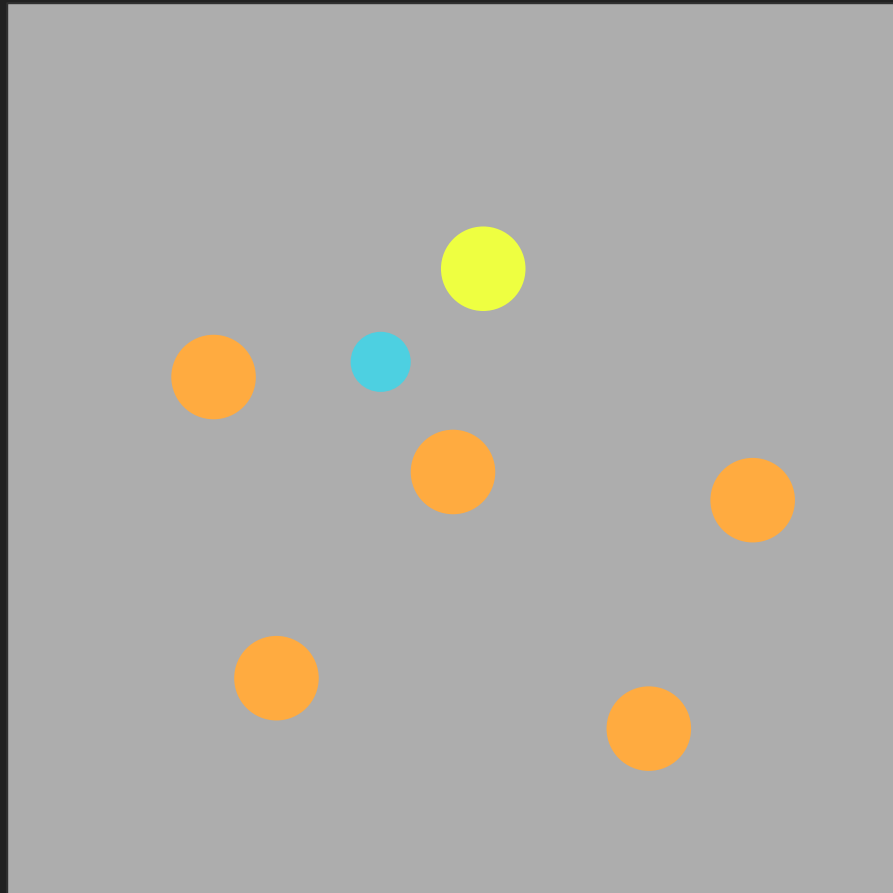
Palet breton ?

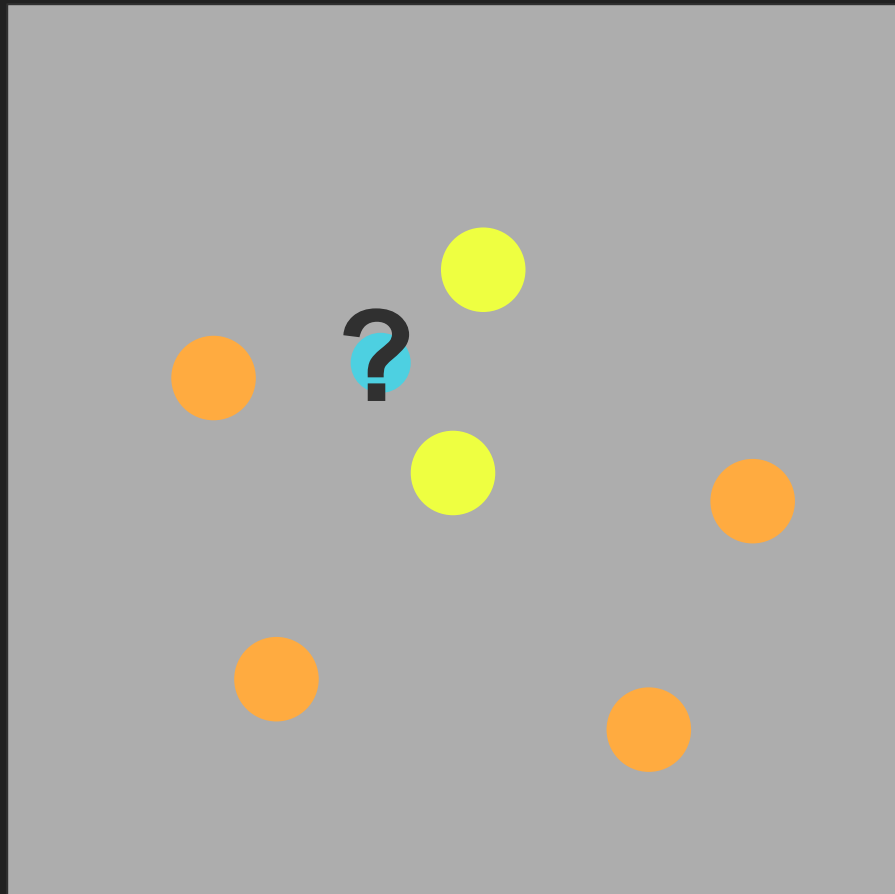








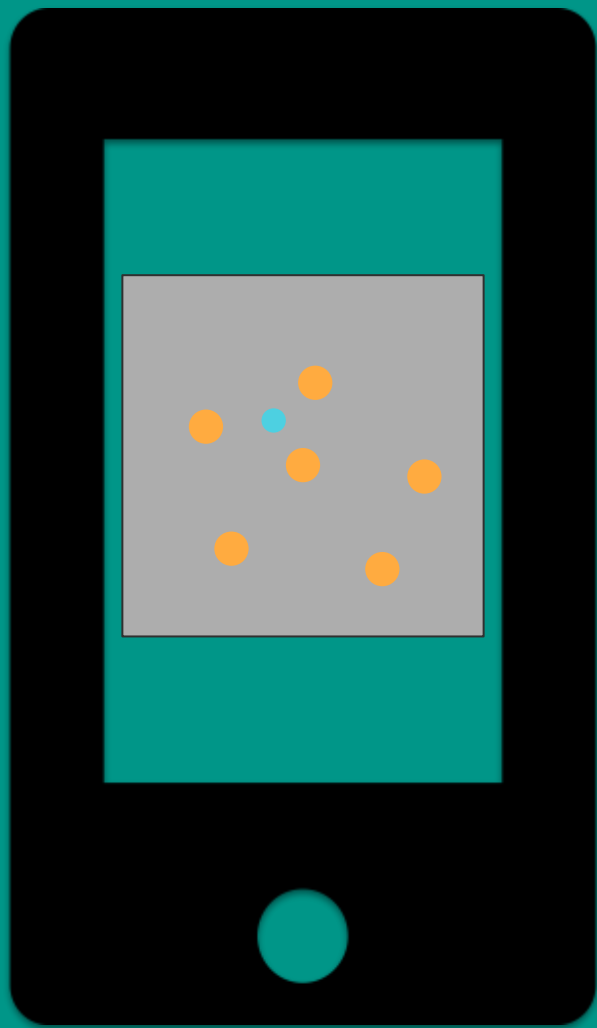


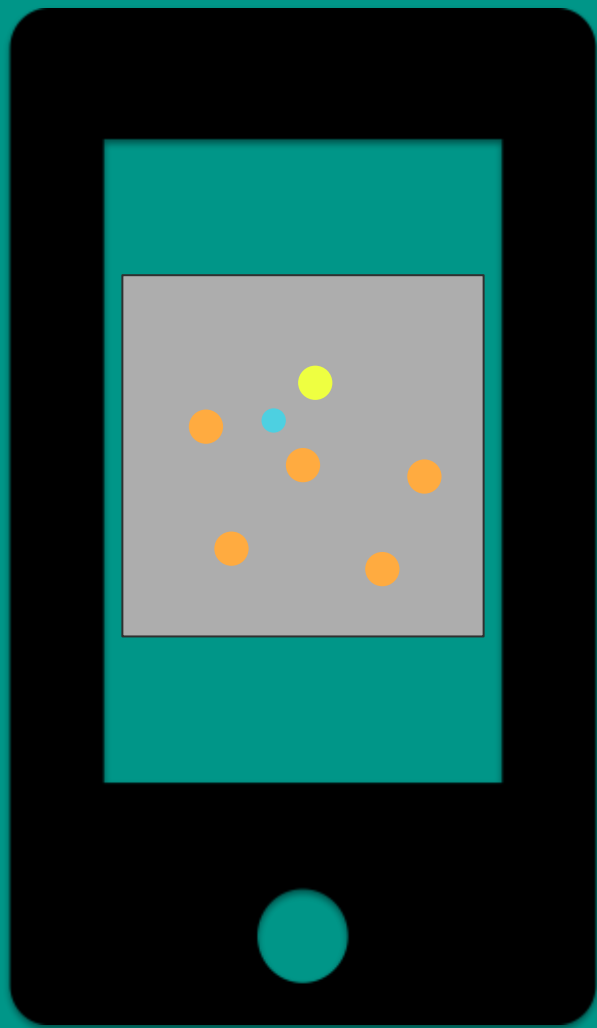






T'as bougé le palet !





C++, OpenCV,
CUDA, SIMD

C++, OpenCV,
CUDA, SIMD

nope

JavaScript

JavaScript



?

JavaScript

+ GPU.js

GPU ?

GPU ?

les shaders !

CPU

DÉFINITION DES COORDONNÉES

GPU

CPU

CPU

DÉFINITION DES COORDONNÉES



VERTEX SHADER

GPU

CPU

CPU

DÉFINITION DES COORDONNÉES



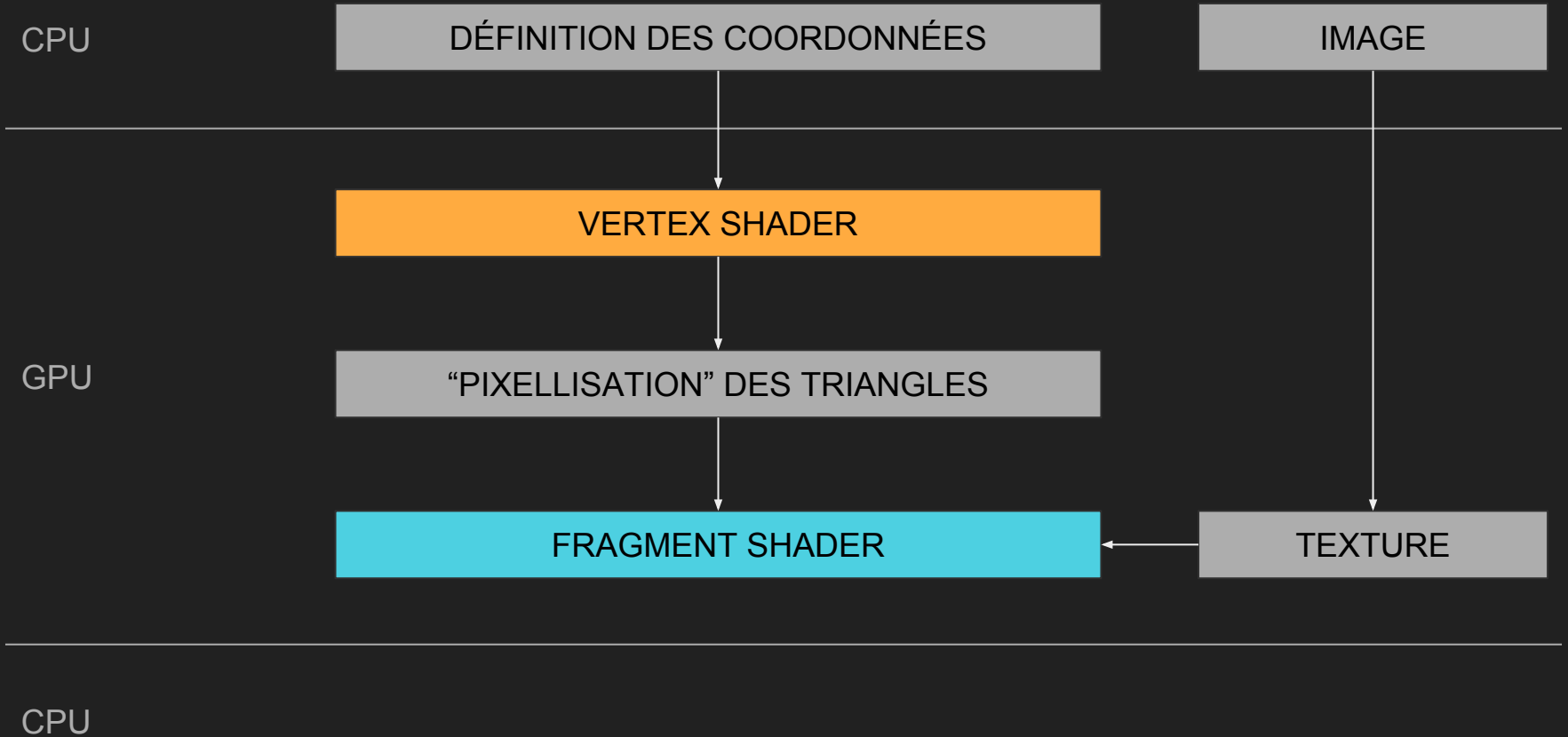
VERTEX SHADER

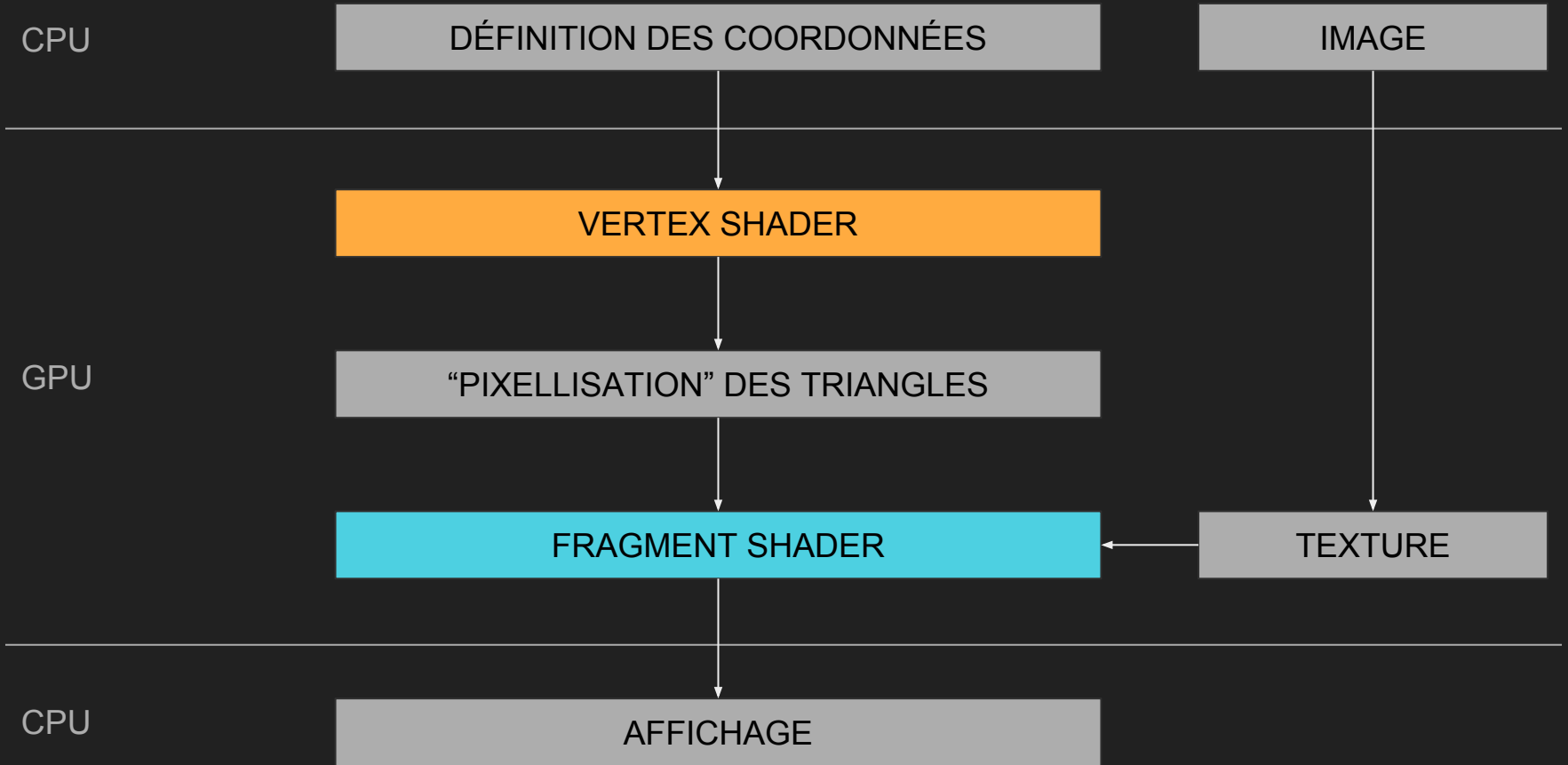


GPU

“PIXELLISATION” DES TRIANGLES

CPU





CPU

IMAGE

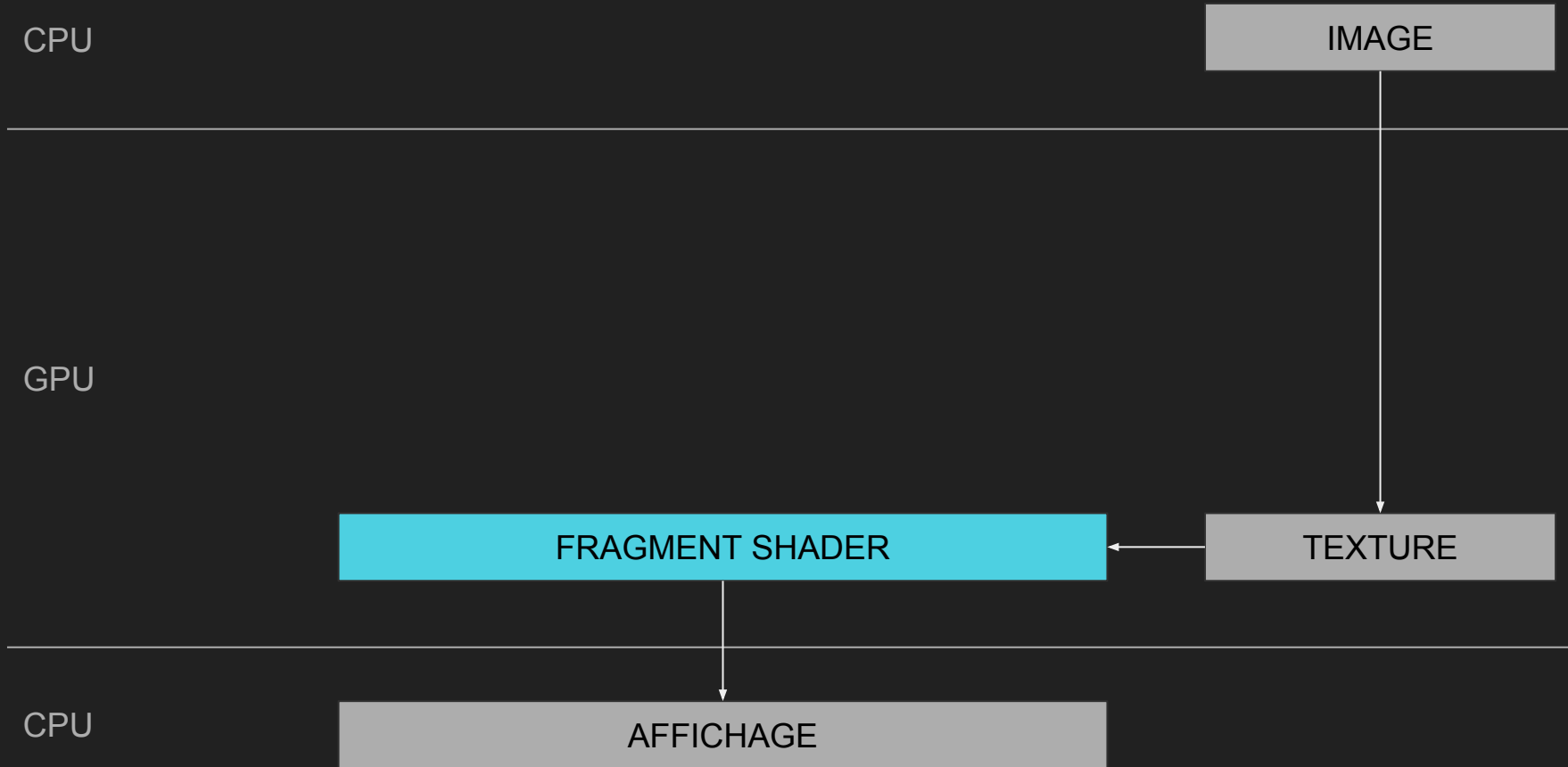
GPU

FRAGMENT SHADER

TEXTURE

CPU

AFFICHAGE



CPU

PARAMÈTRES

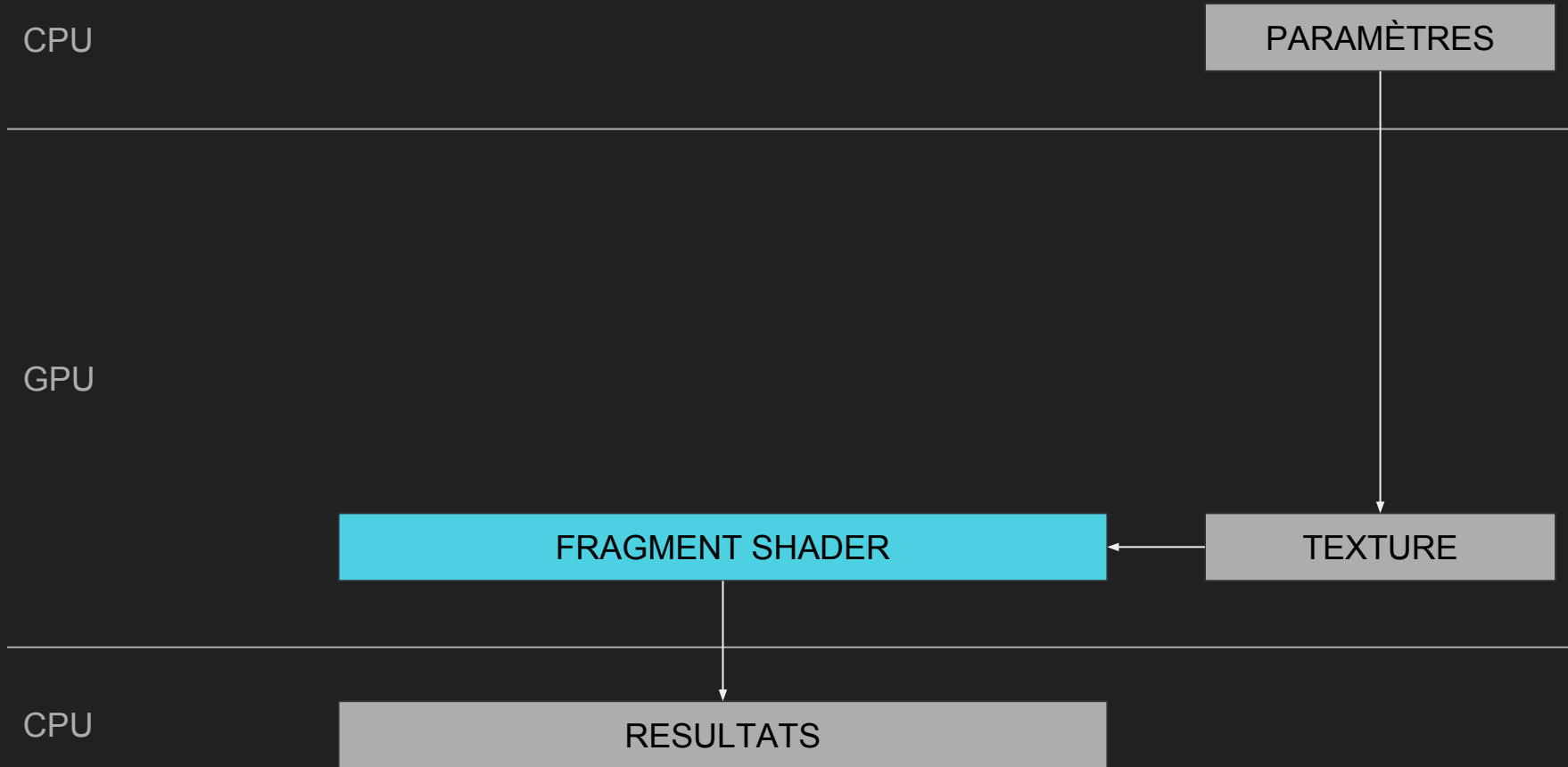
GPU

FRAGMENT SHADER

TEXTURE

CPU

RESULTATS



CPU

JAVASCRIPT

PARAMÈTRES

GPU

FRAGMENT SHADER

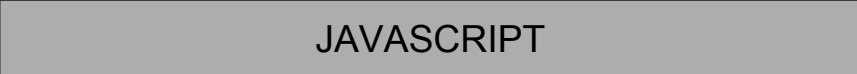
TEXTURE

CPU

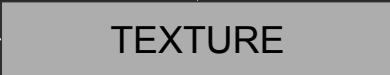
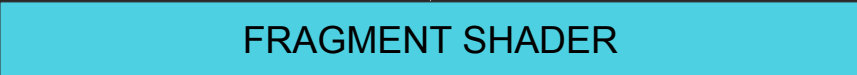
RESULTATS



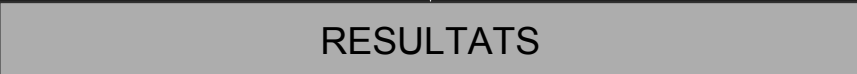
CPU



GPU



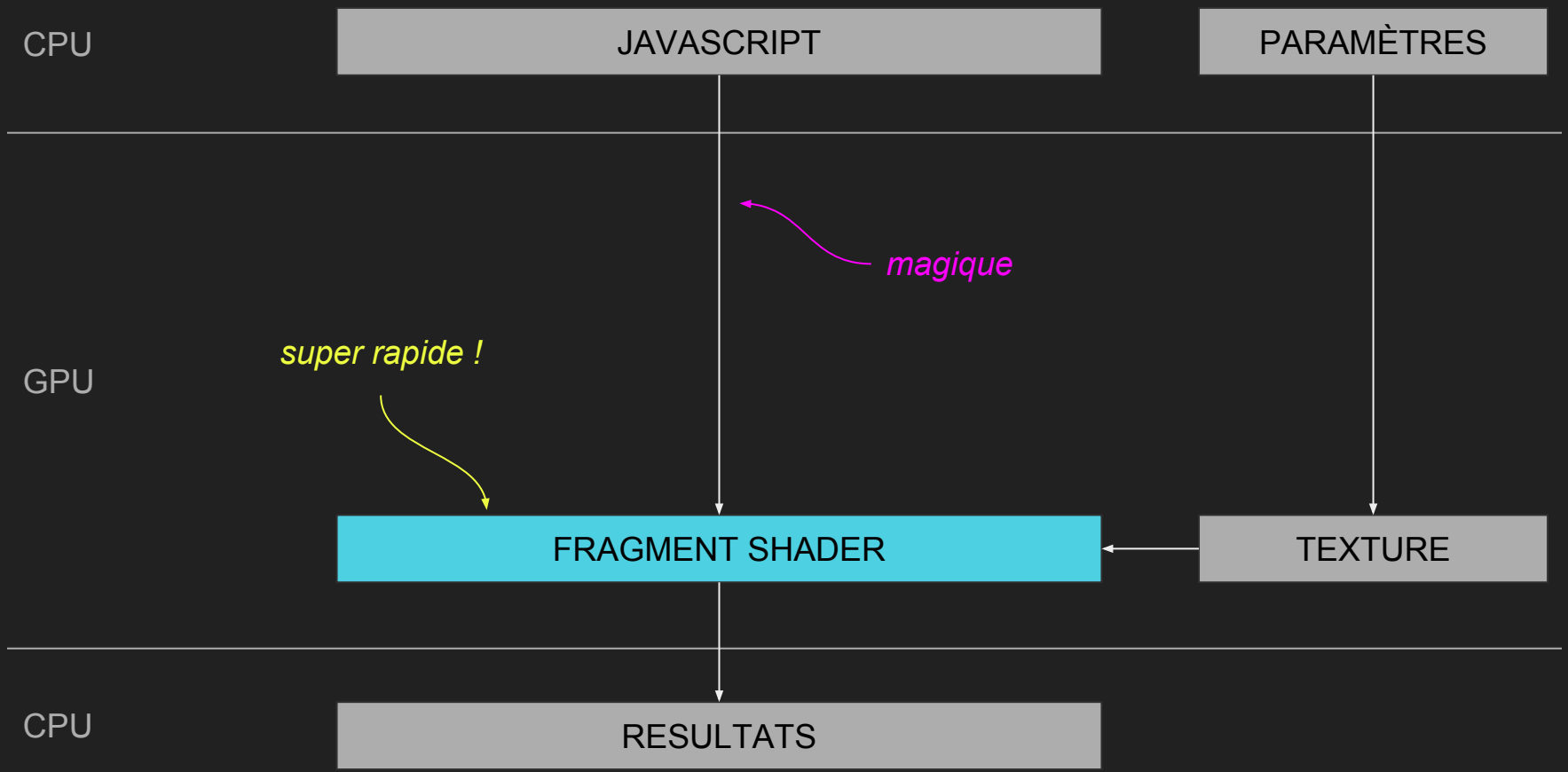
CPU

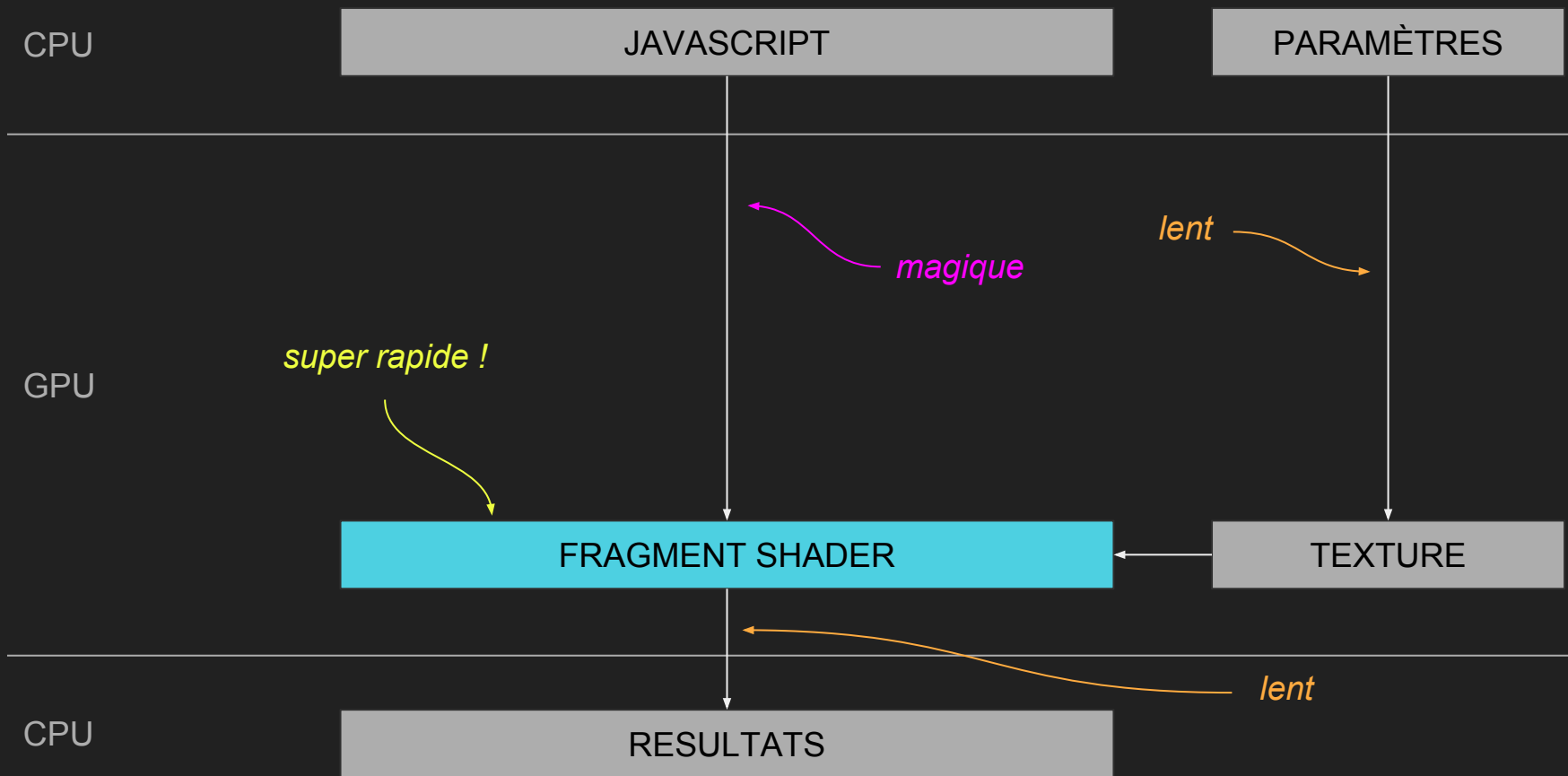


magique



A pink arrow points from the word "magique" to the vertical arrow connecting "JAVASCRIPT" and "FRAGMENT SHADER".





```
const gpu = new GPU();
```

```
//initialisation du shader et définition de fonctions utilitaires
```



```
const gpu = new GPU();
```

```
const multiplyMatrix =  
gpu.createKernel(function(a, b) {  
    //TODO  
}).setOutput([512, 512]);
```

```
//initialisation du shader et définition de fonctions utilitaires
```

```
uniform highp sampler2D user_a;  
uniform highp vec2 user_aSize;  
uniform highp vec3 user_aDim;
```

```
uniform highp sampler2D user_b;  
uniform highp vec2 user_bSize;  
uniform highp vec3 user_bDim;
```

```
void kernel() {  
    //TODO  
}
```

```
const gpu = new GPU();

const multiplyMatrix =
gpu.createKernel(function(a, b) {
    var sum = 0;
    for (var i = 0; i < 512; i++) {
        sum += a[this.thread.y][i] *
            b[i][this.thread.x];
    }
    return sum;
}).setOutput([512, 512]);
```

```
//initialisation du shader et définition de fonctions utilitaires
```

```
uniform highp sampler2D user_a;
uniform highp vec2 user_aSize;
uniform highp vec3 user_aDim;
```

```
uniform highp sampler2D user_b;
uniform highp vec2 user_bSize;
uniform highp vec3 user_bDim;
```

```
highp float kernelResult = 0.0;
```

```
void kernel() {
    float user_sum=0.0;
    for (float user_i=0.0; (user_i<512.0); user_i++){
        user_sum+=(
            get(user_a, vec2(user_aSize[0],user_aSize[1]),
                vec3(user_aDim[0],user_aDim[1],user_aDim[2]),
                threadIdx.y, user_i) *
            get(user_b, vec2(user_bSize[0],user_bSize[1]),
                vec3(user_bDim[0],user_bDim[1],user_bDim[2]),
                user_i, threadIdx.x)
        );
    }
    kernelResult = user_sum;
    return;
}
```

```
const c = multiplyMatrix(a, b);
```

```
uniform highp vec3 uOutputDim;  
uniform highp vec2 uTexSize;  
varying highp vec2 vTexCoord;  
  
void main(void) {  
    index =  
        floor(vTexCoord.s * float(uTexSize.x)) +  
        floor(vTexCoord.t * float(uTexSize.y)) *  
        uTexSize.x;  
    threadId = indexTo3D(index, uOutputDim);  
    kernel();  
    gl_FragColor = encode32(kernelResult);  
}
```

0.532s

0.196s

x2.72 sur PC

4.301s

0.304s

x14.13 sur smartphone

The algorithm

PRISE DE PHOTO

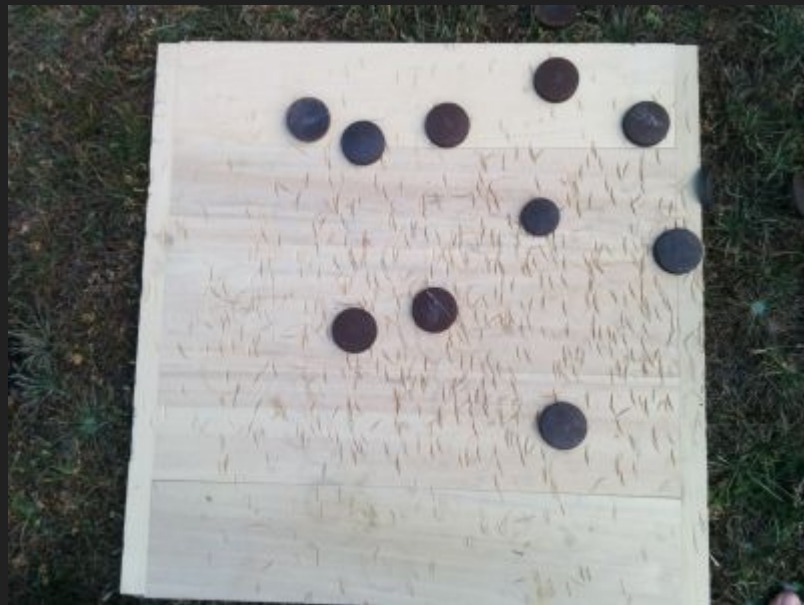
DÉTECTION DE CONTOUR (SOBEL)

DÉTECTION DE CERCLES

PLUS PETIT CERCLE

GRAND CERCLE LE PLUS PROCHE DU PETIT

AFFICHAGE



PRISE DE PHOTO

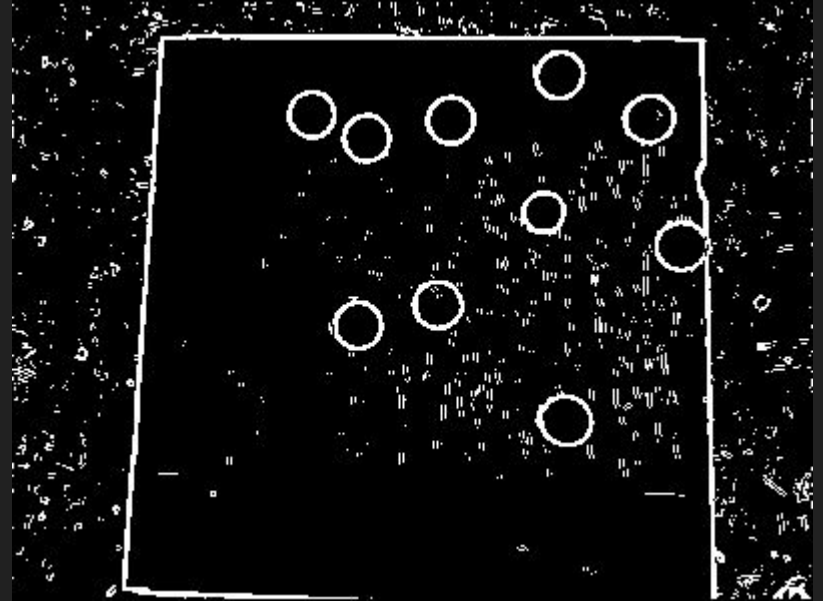
DÉTECTION DE CONTOUR (SOBEL)

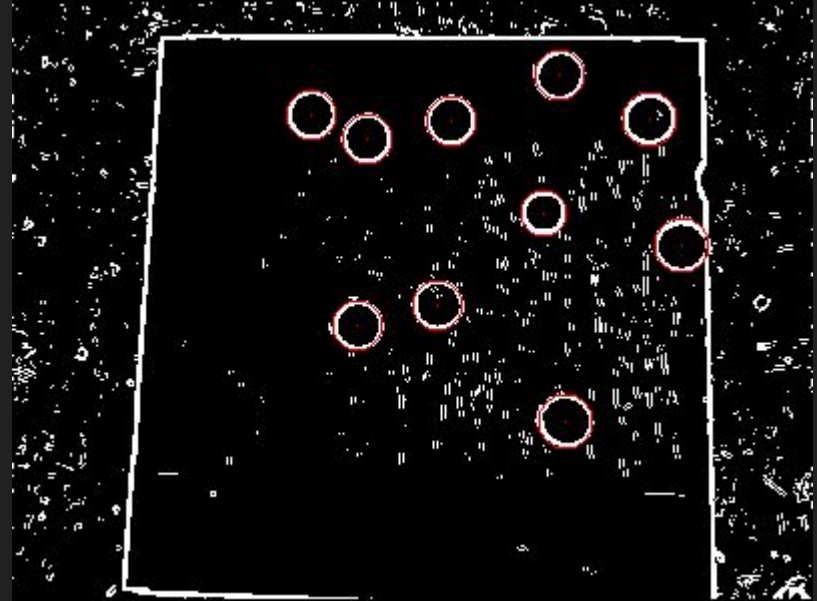
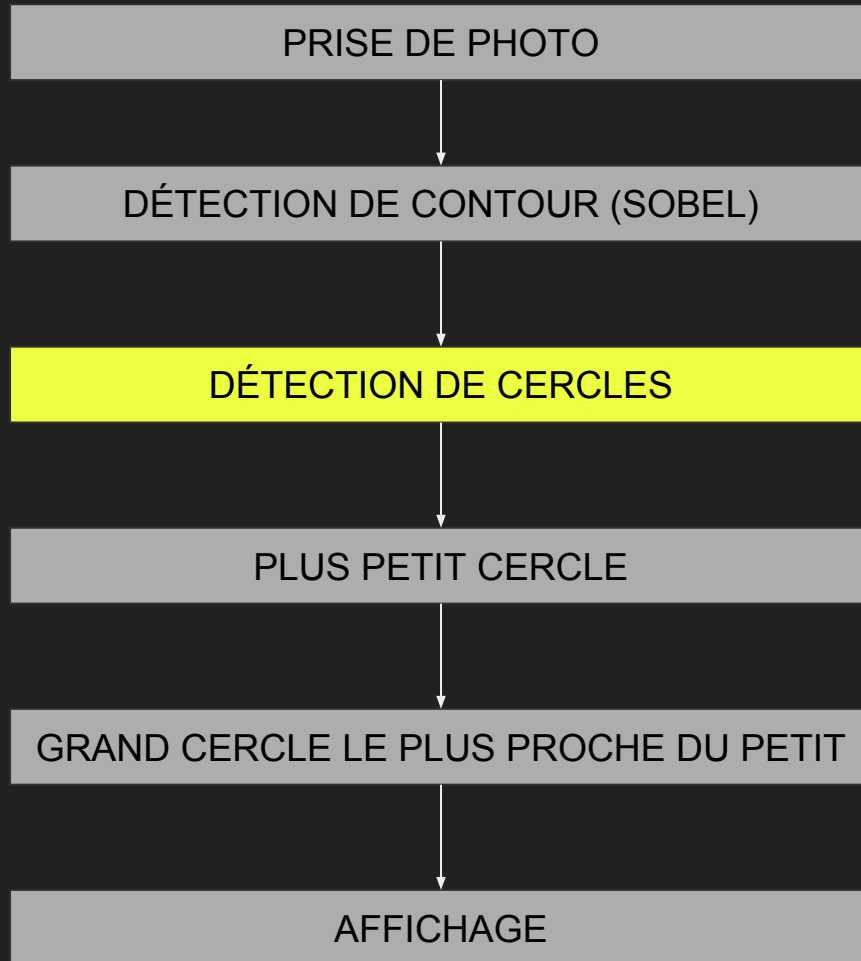
DÉTECTION DE CERCLES

PLUS PETIT CERCLE

GRAND CERCLE LE PLUS PROCHE DU PETIT

AFFICHAGE





PRISE DE PHOTO

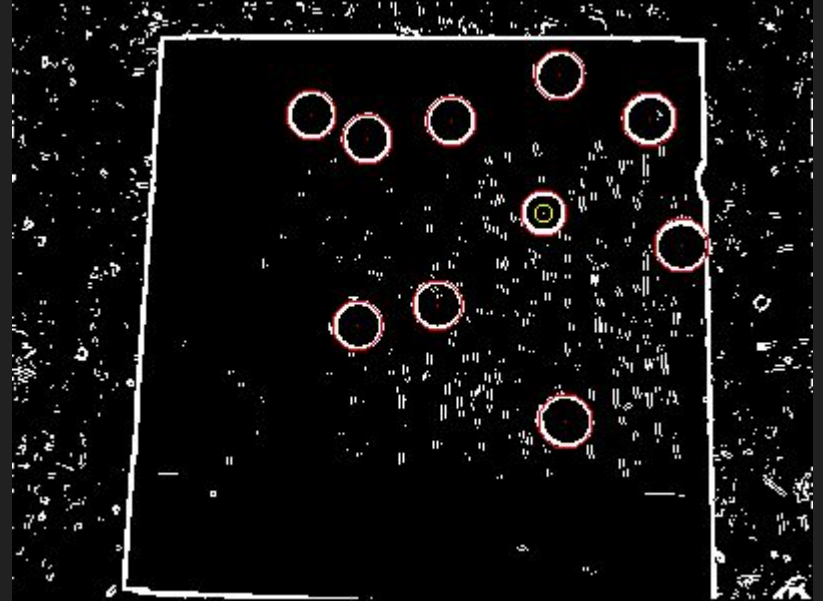
DÉTECTION DE CONTOUR (SOBEL)

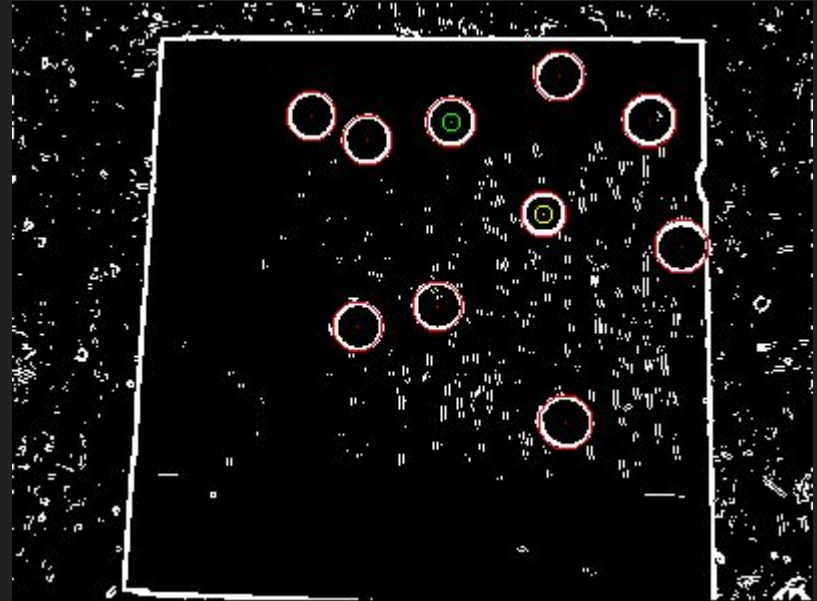
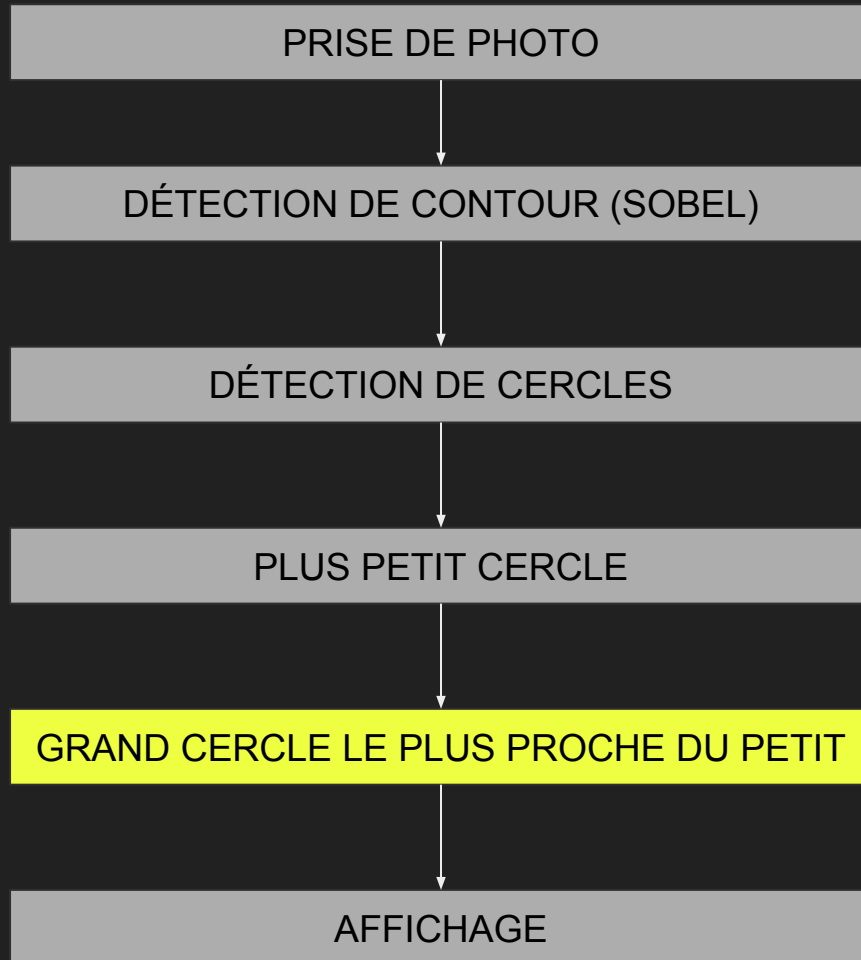
DÉTECTION DE CERCLES

PLUS PETIT CERCLE

GRAND CERCLE LE PLUS PROCHE DU PETIT

AFFICHAGE





PRISE DE PHOTO

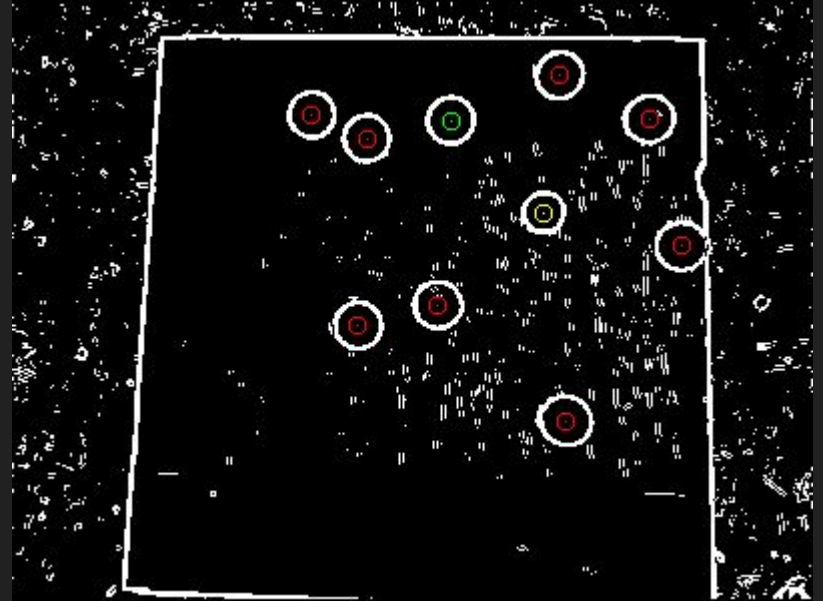
DÉTECTION DE CONTOUR (SOBEL)

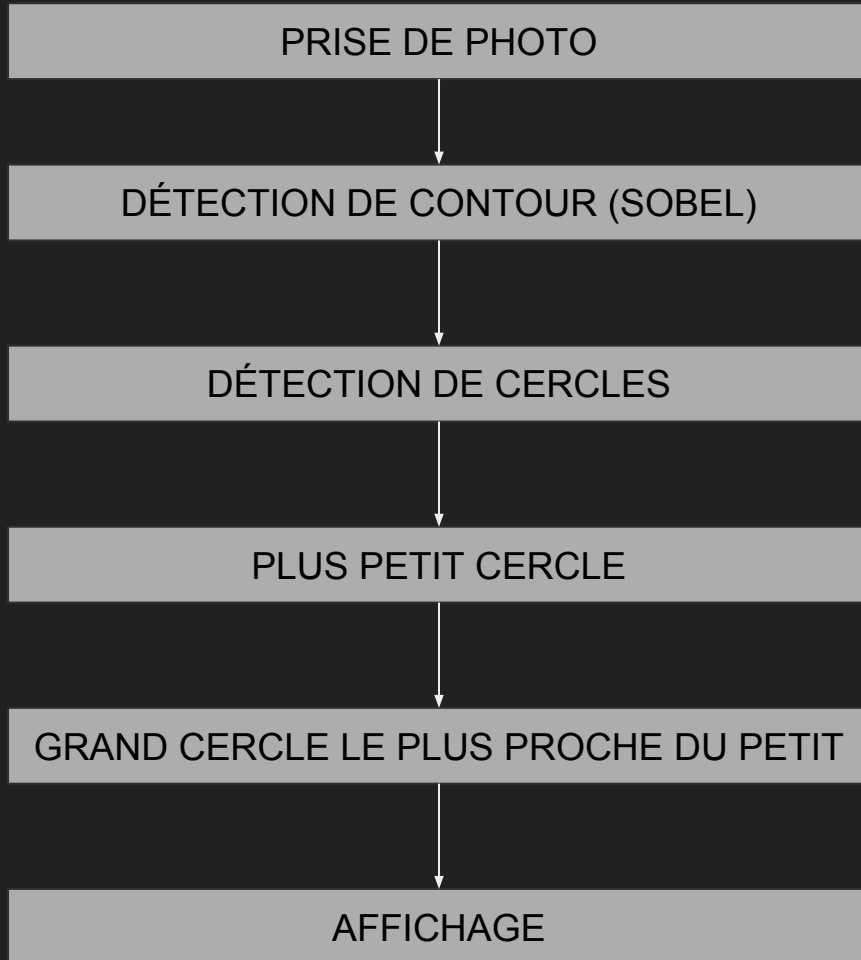
DÉTECTION DE CERCLES

PLUS PETIT CERCLE

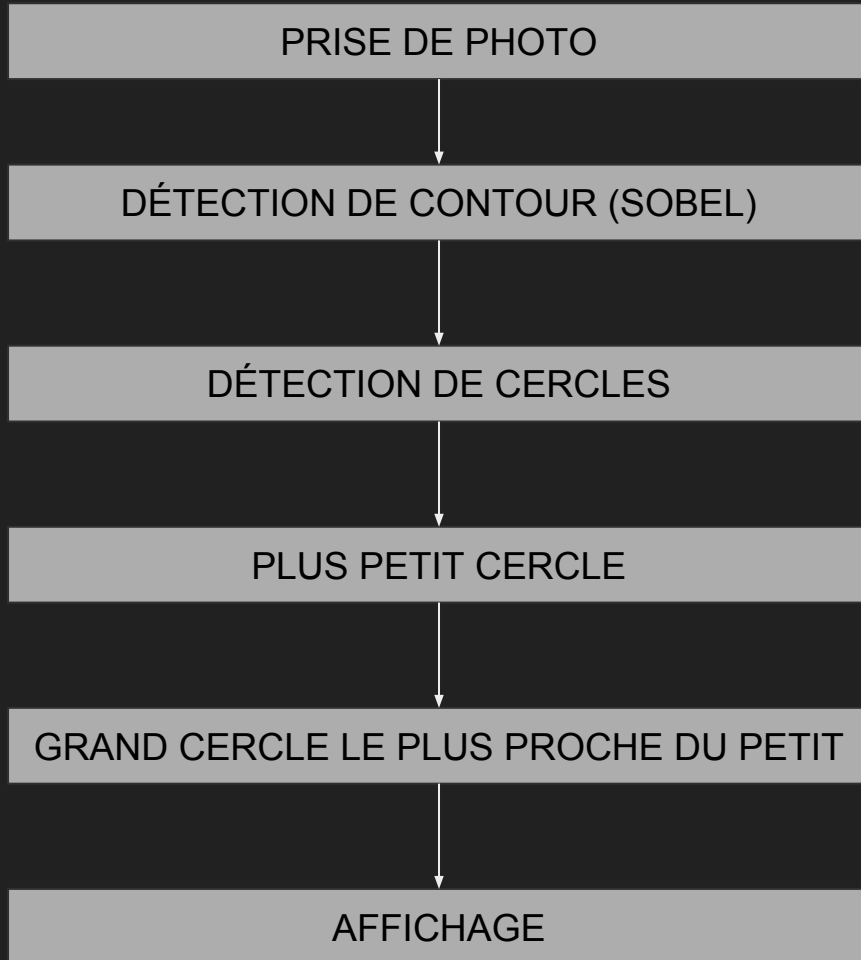
GRAND CERCLE LE PLUS PROCHE DU PETIT

AFFICHAGE



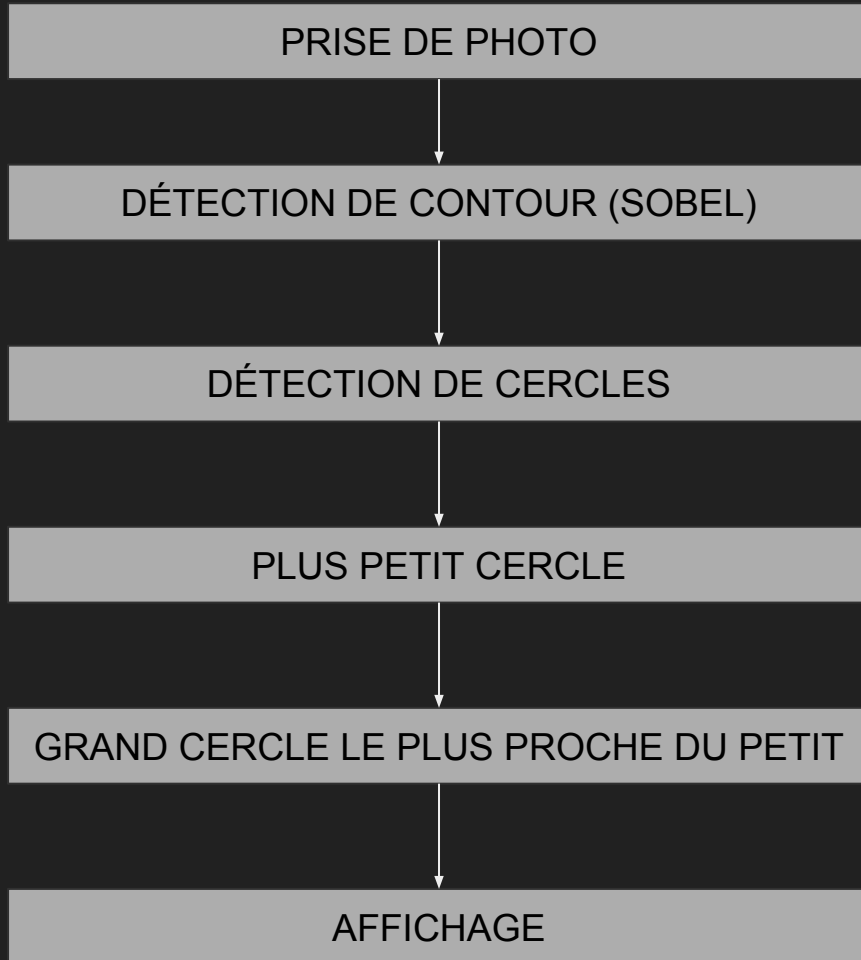


```
<input type='file' accept='image/*' capture='camera' />
```



```
<input type='file' accept='image/*' capture='camera' />
```

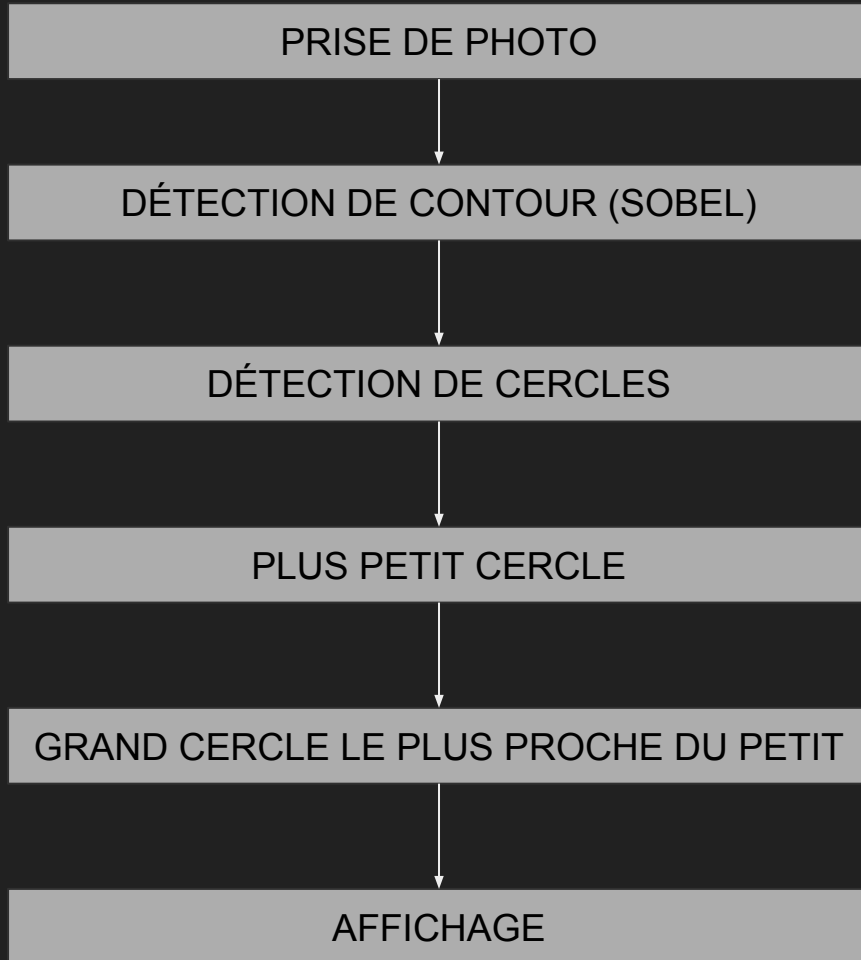
```
> npm install sobel
```



```
<input type='file' accept='image/*' capture='camera' />
```

```
> npm install sobel
```

```
var smallestCircle =  
minBy(circles, c => c.radius)
```

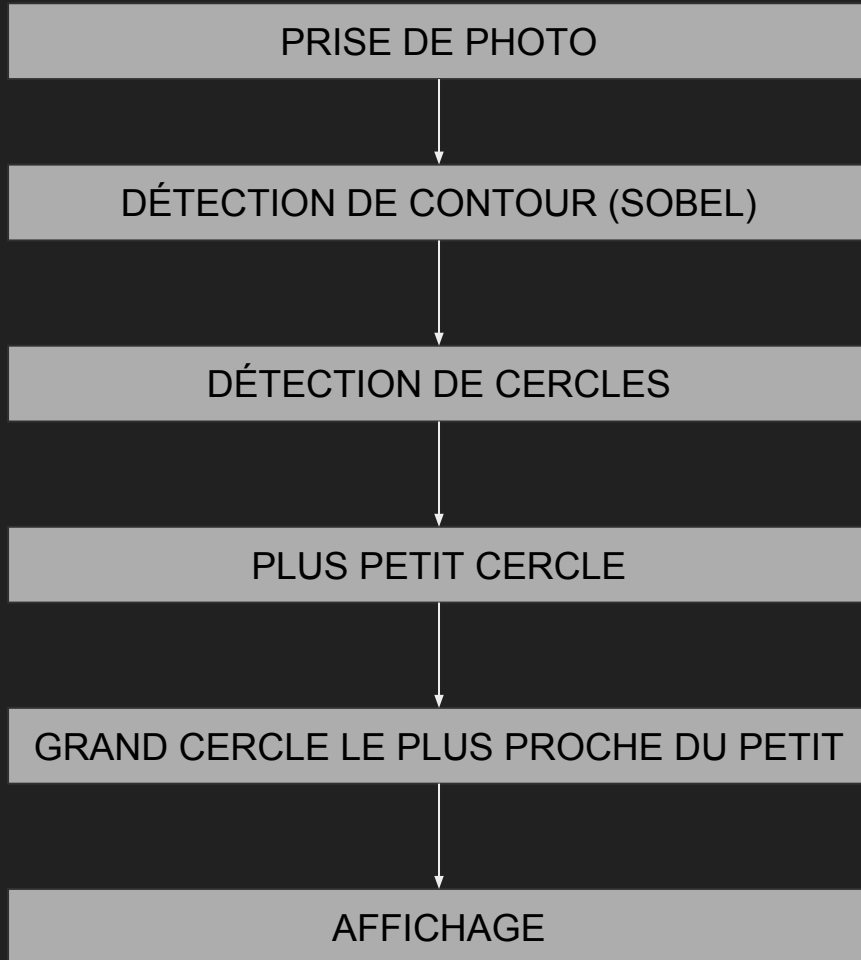


```
<input type='file' accept='image/*' capture='camera' />
```

```
> npm install sobel
```

```
var smallestCircle =  
minBy(circles, c => c.radius)
```

```
var nearestCircle =  
minBy(otherCircles, c => squareDistance(c, smallestCircle))
```

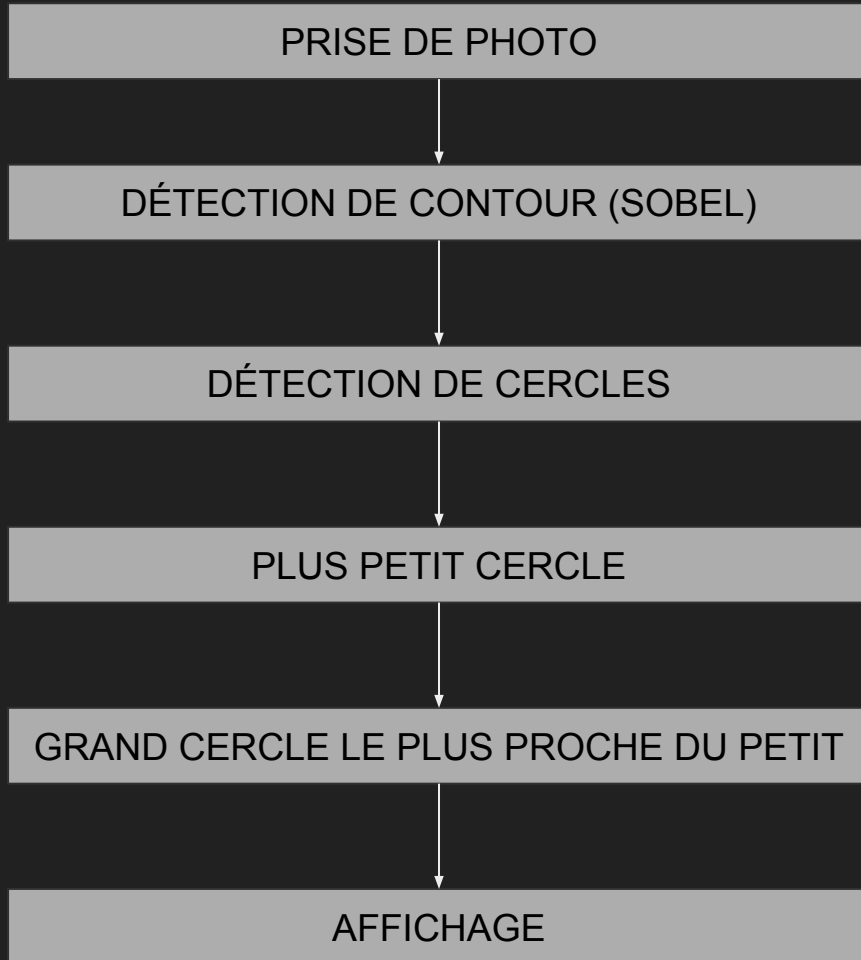
```
<input type='file' accept='image/*' capture='camera' />
```

```
> npm install sobel
```

```
var smallestCircle =  
minBy(circles, c => c.radius)
```

```
var nearestCircle =  
minBy(otherCircles, c => squareDistance(c, smallestCircle))
```

```
<img src={imageDataEncodedInBase64} />
```



```
<input type='file' accept='image/*' capture='camera' />
```

```
> npm install sobel
```

← CA SE COMPLIQUE ICI

```
var smallestCircle =  
minBy(circles, c => c.radius)
```

```
var nearestCircle =  
minBy(otherCircles, c => squareDistance(c, smallestCircle))
```

```
<img src={imageDataEncodedInBase64} />
```

HOUGH TRANSFORM

ou comment éviter de parcourir tous les pixels

		3	2	2		2		2	2
	2	2	2	2	2		2	2	2
1	2	2	2	2	2	2	2	2	2
2	2		2	2	4	4	4	2	2
3		2		2	4	16	4	2	
2	2		2	2	4	4	4	2	2
1	2	2	2	2	2	2	2	2	2
	2	2	2	2	2		2	2	2
		3	2	2		2		2	2

		3	2	2		2		2	2
	2	2	2	2	2		2	2	2
1	2	2	2	2	2	2	2	2	2
2	2		2	2	4	4	4	2	2
3		2		2	4	16	4	2	
2	2		2	2	4	4	4	2	2
1	2	2	2	2	2	2	2	2	2
	2	2	2	2	2		2	2	2
		3	2	2		2		2	2

2.065 s

sur PC

5.346 s

sur smartphone

Difficilement parallélisable

trop compliqué à mon goût

BRUTE FORCE

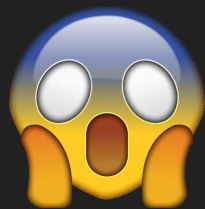
ou comment parcourir tous les pixels

Premiers essais

7.080 s

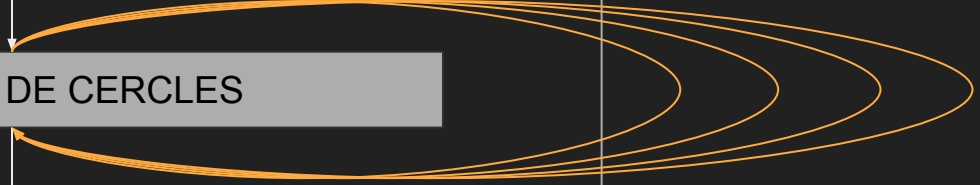
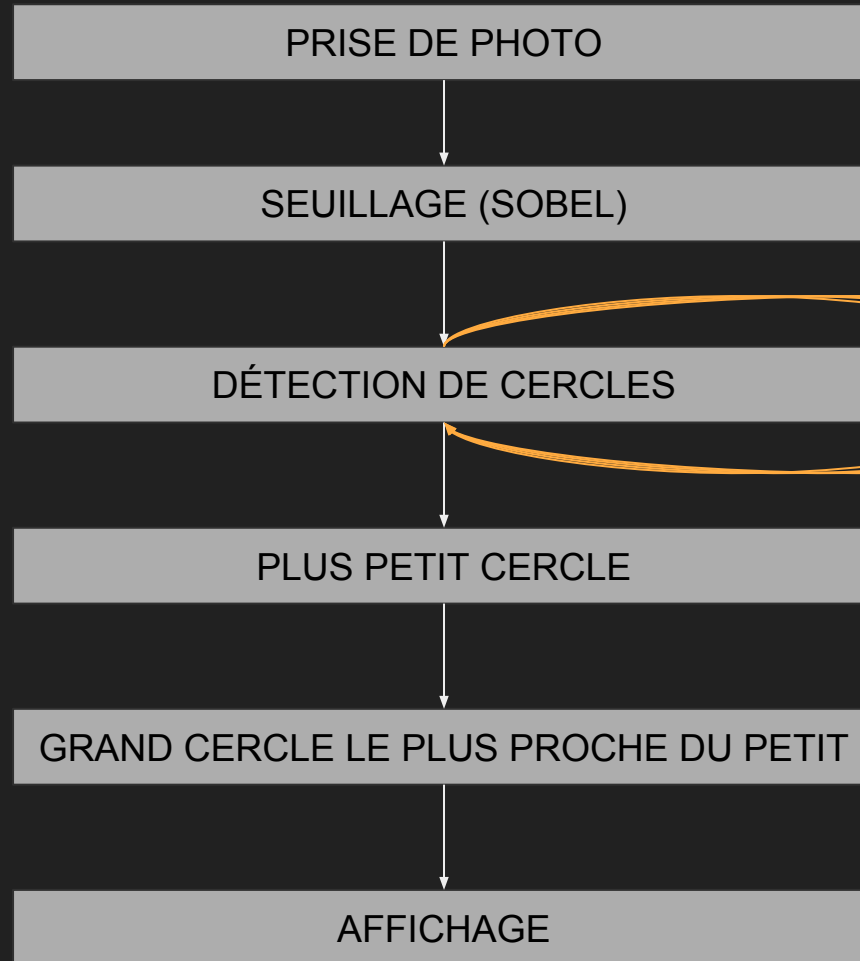
sur PC

7.080 s



CPU

GPU



Limiter les allers-retours

Fusionner les étapes (kernels)

Pour **chaque** rayon :

Executer Hough Transform

Identifier les cercles potentiels

Merger avec les résultats précédents

Limiter les allers-retours

Fusionner les étapes (kernels)

Pour **tous les** rayons :

Executer Hough Transform

Identifier les cercles potentiels

Merger avec les résultats précédents

Limiter les allers-retours

Brancher la sortie d'une étape
sur l'entrée de la suivante

```
gpu.combineKernels(...)
```



```
const add = gpu.createKernel(function(a, b) {  
    return a[this.thread.x] + b[this.thread.x];  
}).setOutput([20]);
```

```
const multiply = gpu.createKernel(function(a, b)  
{  
    return a[this.thread.x] * b[this.thread.x];  
}).setOutput([20]);
```

```
const ab = add(a, b)
```

aller-retour

```
const result = multiply(ab, c);
```

aller-retour

```
const superKernel = gpu.combineKernels(add,  
multiply, function(a, b, c) {  
    return multiply(add(a, b), c);  
});
```

```
const result = superKernel(a, b, c);
```

aller-retour

1.256 s

sur PC

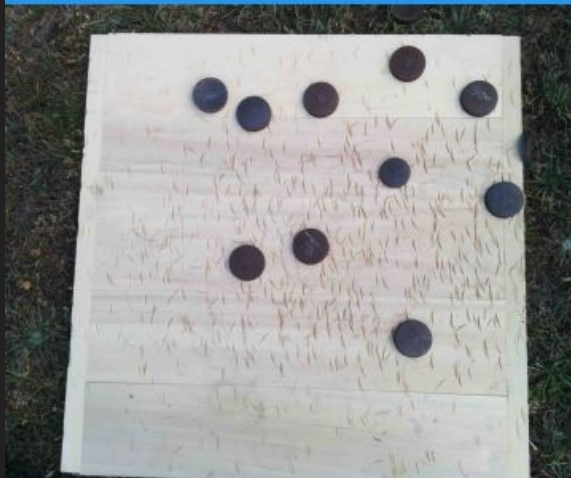
2.112 s


sur smartphone

2.112 s

sur smartphone





 ANALYSER

OU

 TA PHOTO

 UN EXEMPLE

<https://acailly.github.io/palet/>